

DNA Computing Algorithm for a school Timetable Problem

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Deoxyribonucleic acid (DNA) computing is believed to have the potential to offer an effective approach to reduce any NP problem from exponential to polynomial time. Recently, use of biomolecules for solving scheduling problems has gained tremendous attention. In this paper a theoretical proof-of concept algorithm is proposed to address timetable scheduling problem which is a classical NP complete problem. The efficiency of this algorithm owes to the parallel processing property of DNA. Information relating to resources like the set of classes, teachers, time slots and subjects are encoded in the form of unique DNA sequences. Initially, all the possible (valid as well as invalid) allocations are generated and, in each step, the illegal sequences are discarded until finally left out with one or more potential solutions that satisfy the given set of constraints. The time complexity of the proposed algorithm is independent of the size of the problem. Moreover, the proposed algorithm can be applied to solve several other scheduling problems with necessary modifications.

Keywords: DNA; DNA Computing; NP complete problem; Parallelism; Timetable problem.

1. INTRODUCTION

DNA computing is a rapidly evolving area that employs the strands of DNA along with wet lab biochemical reactions for computational purpose. Adleman [1994] recognized the computational power of DNA and demonstrated the first ever experimental solution to an instance of Hamiltonian path problem. After his innovative attempt, DNA computing is witnessing tremendous growth. Lipton [1995] proposed a model to solve the satisfiability problem (SAT). Since then, DNA computing has been receiving enormous attention from researchers working in a wide range of areas. Tides of new models have been proposed since 1994 which are categorized into Adleman-Lipton model, sticker model, restriction enzyme model, self-assembly model and surface-based model, logic gate and Boolean circuit simulation model etc. (Adleman [1998], Lipton [1995], Rowies et al. [1998], Quyang et al. [1997], Winfree et al. [1998], Sakamoto et al. [2000], Smith et al. [1998], Boruah and Dutta [2018]). The parallelism property of DNA has the potential to reduce NP problems from exponential time to polynomial time. Based on this property, several papers have been published suggesting algorithms to solve various NP-complete problems (Li et al. [2006], Xiao et al. [2006], Chang et al. [2012], Wang et al. [2012], Wang et al. [2013], Wang et al. [2014], Chang et al. [2014]).

In this work a theoretical model is proposed to solve an instance of school time table problem using specially encoded strands of DNA. Biochemical operations such as affinity purification, PCR, gel electrophoresis are used as computational tools for the model.

1.1 Related Work in The Field of Timetable Problem

Almost three decades ago Gotlieb [1963] and Even et al. [2002] showed that all timetable problems are NP-Complete. It deals with the task of scheduling faculty (resource person) to deliver lectures to the allotted classes at suitable time slots in accordance with the predefined set of constraints. Over the time, several approaches such as genetic algorithm (Chu and Fang [1999], Cowling et al.

[2002], Sigl et al. [2003], Pezzella et al. [2008], Bhaduri [2009], Ghaemi et al. [2007]), Swarm Optimization (Chu et al. [2006]), agent-based approach (Opera [2007]), combination of simple search and swapping i.e. simple search swapping (Aycan and Ayav [2009]), column generation approach (Huisman [2006]), combination of swarm optimization and local search (Chen and Shih [2013], Zhang et al. [2019]), differential evolution (Zhong et al. [2012]), graph coloring approach (Ganguli and Roy [2017], Redl [2007], Burke et al. [1994], Wood [1968]) etc. have been employed to address such problems.

Beside the above strategies, non-convention techniques such as DNA computing emerged as one of the most interesting candidates due to its inherent parallelism property. Cheng et al. [2010] utilized the DNA tile self-assembly property to solve timetable problems with complexity $O(mn)$. Zhixiang Yin and his co-researchers (Yin and Chen [2010]) demonstrated an easy and feasible model to address timetable problems by employing an innovative technology of Acrydite™ gel separation. Wang et al. [2015] came up with a model to solve an unbalanced assignment problem which ensures applicability to real life situations. Popov et al. [2014] suggested another algorithm to solve timetable problems.

Brute force strategy ensures solution to NP class problems by generating all possible candidate solutions and then each of the candidate is examined for best optimal solution but this strategy suffers from major drawback leading to vast solution space which eventually results in polynomial time (2^n , $n!$ or n^n) search space. DNA computing offers a most convincing solution to overcome these disadvantages owing to its inherent parallelism property.

The organization of this paper is as follows. Section 2 formally describes the proposed algorithm to solve an instance of school timetable by implementing brute force approach in parallel mode. Sub-section 2.1 discusses the theoretical implementation of the proposed algorithm at biochemical level. In sub-section 2.2 the efficiency of the algorithm is investigated in terms of time complexity.

2. DNA ALGORITHM FOR TIMETABLE PROBLEM

A timetable problem is a classical NP-complete problem in which the task is to schedule or allocate resources without any conflict to the given constraints. Every timetable problem has a different set of constraints depending on the requirement, for e.g., an exam scheduling timetable problem has different set of constraints as compared to a class scheduling timetable problem.

In this paper, a new non-deterministic algorithm has been proposed to solve the problem of school timetable scheduling using the parallel processing capacity of DNA. Initially, a set of information needed to be gathered relating to each teachers preference so that a known set is formed. Later on, a set of constraints are formulated according to the requirement. For simplicity of explaining, the authors have considered a special case of a school timetable where:

Information relating to each teachers preference is gathered initially:

- (1) Subject interests of the teachers along with the classes or semesters they are interested in teaching those subjects, i.e., if a teacher has a subject interest as science then he has to mention the class he is interested in teaching (for e.g., Science of class XII)
- (2) Preferred time slots of each teacher must be acquired in such a way that the total number of preferred time slots is always greater or equal to the number of subjects needed to be taught by each teacher (preferred time slots of each teacher \geq number of subjects needed to be taught by each teacher).

Set of constraints for the proposed algorithm:

- (1) Not more than one teacher should be allocated to the same class at the same time slot.
- (2) All the subjects should be taught to each class exactly once every day.
- (3) No class should remain unallocated at any time slot.

The problem is to allot time slots to each teacher according to their preferences without conflicting with the time slots of other teacher assigned to the same class. For e.g., if a teacher T_1

has been assigned subjects S_1 and S_2 to be taught to class C_1 and C_3 respectively then, while formulating the timetable care must be taken to ensure allotments in his preferred time slots and to avoid any allotment in his unfavourable subjects or time slots.

The finite set of classes, teachers, subjects and time slots are represented as:

- (1) 'n' numbers of classes: $C = \{C_1, C_2, C_3, \dots, C_n\}$
- (2) 'm' number of teachers: $T = \{T_1, T_2, T_3, \dots, T_m\}$
- (3) 'x' number of subjects: $S = \{S_1, S_2, S_3, \dots, S_x\}$
- (4) 'y' numbers of time slots: $t = \{t_1, t_2, t_3, \dots, t_y\}$

The proposed algorithm:

Step 1: Generate all possible random allotments for each class separately.

Step 2: Select those allotments that include 1st and last time slots.

Step 3: Extract allotments that have correct length.

Step 4: Keep all allocations that have all subjects and time slots at least once.

Step 5: Generate all possible random allotments for the entire time table.

Step 6: Select those allotments that start with 1st class and end with last class.

Step 7: Extract allotments that have correct length.

Step 8: Keep all allotments that have all subjects, time slots and class at least once.

The above-mentioned algorithm is represented in the form of a pseudocode with four procedures as shown below. `DNATimeTable_Main()` (Algorithm 1) is the main procedure from where `EncodeInformation_Strand()` (Algorithm 2), `EncodeSplint_Strand1()` (Algorithm 3), `EncodeSplint_Strand2()` (Algorithm 4) are called.

Biological operations: `Merge()`, `Append()`, `PCR_amplification()`, `Affinity_purification()` and `Extract()` are used to construct the timetable solving problem which are derived from Adleman - Lipton model (Adleman [1994], Lipton [1995]).

The Adleman-Lipton model is constructed upon the following biological operations:

Append (T, S): String S is ligated to the end of all DNA strands in test-tube T.

Copy (T, tt₁, tt₂, , tt_n): Several replicas of DNA strands of test-tube T is created and placed in test-tubes tt₁ to tt_n.

Merge (T, tt₁, tt₂, , tt_n): The contents of test tubes tt₁ to tt_n are poured into tube T and allow them to undergo biochemical reaction.

Extract (T, S, T+, T-): The operation produces two different test-tube T+ and T- depending on the presence or absence of string S respectively.

Detect (T): Given a tube T, this operation returns true if there is at least one DNA strand in T, otherwise it returns false.

Discard (T): Given a tube T, this operation ignores T.

Affinity_purification(T, S, tt): In this operation magnetic beads attached with covalently bonded DNA sequence are used to filter out all those DNAs in tube T that contain S sequence at least once. The extracted sequences are stored in test-tube tt.

The algorithm returns output as either a non-empty set which signifies one or more feasible scheduling schemes or as an empty set which means the corresponding timetable problem doesn't have any solution or valid schedule for the given constraints.

2.1 Biochemical implementation of the proposed algorithm

For simplicity in demonstrating the biochemical implementation of the proposed algorithm, an instance of school timetable with three classes, four teachers, three time slots, and three subjects are considered, which are represented by the notation as (C_1, C_2 and C_3), (T_1, T_2, T_3, T_4), (t_1, t_2, t_3) and (S_1, S_2, S_3) respectively. Table I show the outline of the desired timetable.

Information relating to each teachers preference:

The following dummy information relating to the subjects and class preferences (Figure 1) is assumed to be collected from each teacher before the execution of the algorithm that is represented

Algorithm 1: Pseudocode for solving the time table problem

```

DNATimeTable_Main()
Begin
increment_value = 1
Empty (tt_info, tt_splint1, tt_splint2, tt_info, tt_1k, tt_2k, tt_3k, tt_4k, tt_result, tt_final_result)
EncodeInformation_Strand1()
EncodeInformation_Strand2()
{
for (k ← 1 to n, increment_value) do
{
Merge(tt_1k, tt_splint1, tt_info)
PCR_amplification(tt_1k,  $\bar{C}_n$ ,  $\bar{C}_n$ )
Extract(tt_1k, 170bp, tt_2k)
for (i ← 1 to x, increment_value) do
{
Affinity_purification(tt_2k,  $\bar{S}_x$ , tt_3)
}
end for
for (j ← 1 to t, increment_value) do
{
Affinity_purification(tt_3,  $\bar{t}_j$ , tt_4)
}
end for
Merge(tt_all, tt_splint2, tt_4)
PCR_amplification(tt_all,  $\bar{C}_1$ ,  $\bar{C}_n$ )
Extract(tt_all, 510bp, tt_result)
for (k ← 1 to m, increment_value) do
{
Affinity_purification(tt_result,  $\bar{T}_m$ - $\bar{t}_y$ , tt_final_result)
}
end for
}
end for
}
End

```

as $T_m \rightarrow S_x(C_n)$ i.e. teacher T_m interested in teaching subject S_x to class C_n . Similarly, preference of time slots is shown in Figure 2 which is represented as $T_m \rightarrow t_y$, i.e. Teacher T_m prefers to teach in time slot t_y .

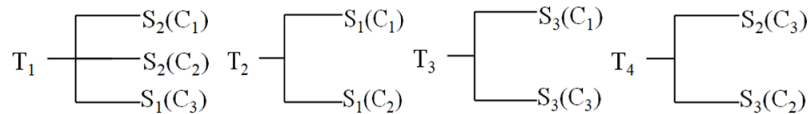


Figure 1: Subject preferences of each teacher ($T_m \rightarrow S_x(C_n)$).

As the entire algorithm is conceptualized to realize in the wet lab, all inputs (collected information and constraints) are translated in the form of strands of DNA. To attain this, each of the notations such as C_1 , C_2 , C_3 , T_1 , T_2 , T_3 , T_4 , S_1 , S_2 , S_3 , t_1 , t_2 , and t_3 are pre-assigned with

Algorithm 2: Procedure for encoding teacher information strand

```

EncodeInformation_Strand()
Begin
  for ( $j \leftarrow 1$  to  $m$ ,  $\text{increment\_value}$ ) do
    {
      ligate( $\text{time\_slot}$ )
      Begin
      if ( $\text{time\_slot} == \text{first}$ ) then
         $\text{tt\_info} \leftarrow 3' \text{-} C_n \text{-} t_y \text{-} C_n \text{-} S_x \text{-} T_j \text{-} t_y \text{-} 5'$ 
      end if
      if ( $\text{time\_slot} == \text{last}$ ) then
         $\text{tt\_info} \leftarrow 3' \text{-} t_y \text{-} C_n \text{-} S_x \text{-} T_j \text{-} t_y \text{-} C_n \text{-} 5'$ 
      else
         $\text{tt\_info} \leftarrow 3' \text{-} t_y \text{-} C_n \text{-} S_x \text{-} T_j \text{-} t_y \text{-} 5'$ 
      end if
      End
    }
  end for
End

```

Algorithm 3: Procedure for encoding splint strand for every class separately

```

EncodeSplint_Strand1()
Begin
  for ( $i \leftarrow 1$  to  $y$ ,  $\text{increment\_value}$ ) do
    {
      ligate( $\text{tt\_splint1}, \bar{t}_1, \bar{t}_{i+1}$ )
    }
  end for
End

```

Algorithm 4: Procedure for encoding splint strand for all the classes together (entire time-table)

```

EncodeSplint_Strand2()
Begin
  for ( $i \leftarrow 1$  to  $n$ ,  $\text{increment\_value}$ ) do
    {
      ligate( $\text{tt\_splint2}, \bar{C}_1, \bar{C}_{i+1}$ )
    }
  end for
End

```

Table I. Instance of a School Time Table

Class	Time slot		
	(9-10 AM) t_1	(10-11 AM) t_2	01-02 PM) t_3
C_1			
C_2			
C_3			

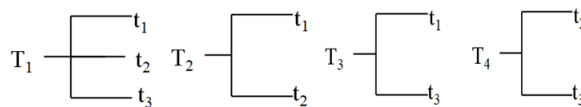


Figure 2: Time slots preferences of each teacher ($T_m \rightarrow t_y$).

Table II. Encoding of information strand for each teacher

T_m	Information Strand	
T ₁	t_1 (where $y = 1$)	3'-C ₁ -t ₁ -C ₁ -S ₂ -T ₁ -t ₁ -5' 3'-C ₂ -t ₁ -C ₂ -S ₂ -T ₁ -t ₁ -5' 3'-C ₃ -t ₁ -C ₃ -S ₂ -T ₁ -t ₁ -5'
	t_2 (where $y = 2$)	3'-t ₂ -C ₁ -S ₂ -T ₁ -t ₂ -5' 3'-t ₂ -C ₂ -S ₂ -T ₁ -t ₂ -5' 3'-t ₂ -C ₃ -S ₁ -T ₁ -t ₂ -5'
	t_3 (where $y = 3$)	3'-t ₃ -C ₁ -S ₂ -T ₁ -t ₃ -C ₁ -5' 3'-t ₃ -C ₂ -S ₂ -T ₁ -t ₃ -C ₁ -5' 3'-t ₃ -C ₃ -S ₁ -T ₁ -t ₃ -C ₁ -5'
T ₂	t_1 (where $y = 1$)	3'-C ₁ -t ₁ -C ₁ -S ₁ -T ₂ -t ₁ -5' 3'-C ₂ -t ₁ -C ₂ -S ₁ -T ₂ -t ₁ -5'
	t_2 (where $y = 2$)	3'-C ₂ -C ₁ -S ₁ -T ₂ -t ₂ -5' 3'-t ₂ -C ₁ -S ₁ -T ₂ -t ₂ -5'
T ₃	t_1 (where $y = 1$)	3'-C ₁ -t ₁ -C ₁ -S ₃ -T ₃ -t ₁ -5' 3'-C ₃ -t ₁ -C ₃ -S ₃ -T ₃ -t ₁ -5'
	t_3 (where $y = 3$)	3'-t ₃ -C ₁ -S ₃ -T ₃ -t ₃ -C ₁ -5' 3'-t ₃ -C ₃ -S ₃ -T ₃ -t ₃ -C ₃ -5'
T ₄	t_2 (where $y = 2$)	3'-t ₂ -C ₂ -S ₃ -T ₄ -t ₂ -5' 3'-t ₂ -C ₃ -S ₂ -T ₄ -t ₂ -5'
	t_3 (where $y = 3$)	3'-t ₃ -C ₂ -S ₃ -T ₄ -t ₃ -C ₂ -5' 3'-t ₃ -C ₃ -S ₂ -T ₄ -t ₃ -C ₃ -5'

fixed length 10-mer random but unique sequence of DNA. On execution of procedure Encode-Information_Strand(), the derived information of each teacher are translated to single strands of DNA. Table II shows the encoded information of each teacher depending on the allocation of time slots. The encoding at the 1st time slot has C_n at 3'end whereas the encoding at the last time slot has C_n at 5'end. All the intermediate time slots do not have C_n at any of its extreme ends.

The biochemical reaction corresponding to each class is executed in a separate test tube.

To generate all possible combinations, two sets of DNA sequences are used as splints, i.e., Splint1 and splint2; Splint1 is used to generate combinations of allotments corresponding to each class (see Table III) whereas splint2 is used to generate all possible combinations of allotments for the entire timetable (see Table IV).

Splint1 is obtained by ligating complements of t_y and complement of t_{y+1} sequence i.e., $5'\bar{t}_y\bar{t}_{y+1}3'$ (see Table III). This 20-mer oligo sequence works as a splint to bring together the encoded information strands based on simple hybridization reactions (shown in Figure 3).

Step 1 to step 4 dedicated to generate scheduling sequence for individual class (each test-tube

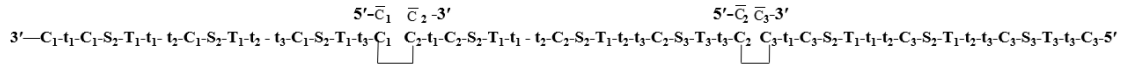


Figure 7: An example of generated allocation pattern for classes C₁, C₂ and C₃.

By the end of step 5 several sets of random combinations are generated consisting of both valid as well as invalid strands. PCR reaction is carried out in the test tube with \bar{C}_1 and \bar{C}_n as primers which result in strands starting with C₁ and ending with C₃.

Step 7: *Extract allotments that have correct length:*

Gel electrophoresis is carried out during this step and the band corresponding to length 510 bp is extracted. Length of valid assignment to all the three classes together = 3* (|C₁| + |C₂| + |C₃|) = 3*170 = 510 bp. Sequences with length more or less than 510 bp are invalid as it represents either repetition of certain allocation or incomplete allocation.

Step 8: *Keep all allotments that have all subjects, time slots and class at least once:*

Affinity purification is carried out on the extracted sequences to discard any conflict of allotment. A conflict of allocation arises if a teacher is allocated to two different classes at the same time slot. To implement this, affinity purification is carried out with 5'- \bar{T}_m - \bar{t}_y -3' sequences conjugated to magnetic beads. If in any sequence there is more than one T_m - t_y sequence then that strand is discarded. The final end products of this step are those strands which represent a valid feasible solution to the timetable problem.

2.2 Evaluating the algorithm in terms of time complexity

Unlike conventional computing, DNA computing involves manipulation of strands of DNA by using relevant biochemical reactions in test tubes. A single test tube solution contains trillions of nucleotide strands that undergo the same reaction at the same time. For e.g., when a hybridization reaction is executed in a test tube, all of the trillion strands in the test tube undergo the reaction at the same time. However, such computing is ineffective in solving tasks which require excessive sequential operation. This property qualifies DNA computing an excellent candidate for exhaustive search and brute force approach to solve NP complete problems in polynomial time. There are several measures to evaluate an algorithm such as time complexity and space complexity. Time complexity which is evaluated by counting the number of biological operations of the algorithm by considering the complexity of every biological operation as O(1) as it is independent of input size i.e., the number of inputs in the form of DNA strands doesn't matter. The time complexity of an algorithm would be the sum of the time complexity of all steps. The time complexity for each step of the proposed algorithm is given in Table V.

Table V. The time complexity for each step of the proposed algorithm

Steps of the algorithm	Time complexity
Step 1	O(1)
Step 2	O(1)
Step 3	O(1)
Step 4	O(n ²)
Step 5	O(1)
Step 6	O(1)
Step 7	O(1)
Step 8	O(n ²)

$$\begin{aligned}
 \text{Total time complexity of the proposed algorithm} &= O(1)+O(1)+O(1)+O(n^2)+O(1)+O(1)+O(1)+O(n^2) \\
 &= O(n^2)
 \end{aligned}$$

3. CONCLUSION

In this paper an algorithm is proposed to solve an instance of time table problem. Due to the parallelism property of DNA, the algorithm is quite effective in large scale input scenario. The total number of steps is fixed and is not affected by the number of inputs therefore the overall efficiency is independent of problem size. Time complexity of this algorithm is in polynomial time i.e., $O(n^2)$, but space complexity eventually becomes a restrictive factor which marked an upper bound to the instance of the experimentally solvable problem. The authors would like to acknowledge that, though from a theoretical point of view this algorithm is implementable as all the operations are doable; however experimental difficulty can't be avoided due to inherent reliability issues in wet lab experiments. In the near future it is expected that DNA timetable scheduling algorithm finds its application in several other scheduling problems with necessary modifications.

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